

Corrosion behavior of pure aluminum in FeCl_3 solution

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Abstract: The corrosion behavior of pure aluminum in FeCl_3 solution was investigated mainly by in-situ AFM (Atomic Force Microscopy). The results of combined researches of AFM, SEM(Scanning Electron Microscopy) and EDAX(Energy Dispersive Analysis of X-ray) show that in addition to uniform attack, pitting corrosion takes place also on pure aluminum surface in FeCl_3 solution at open-circuit potential, and impurity elements Fe and Cu are found enriched in corrosion product. In-situ AFM was also used to examine the initiation and development of pitting corrosion of pure aluminum induced by potentiodynamic sweep, and the repassivation of an active pit is observed. AFM tip scratching technique was used to produce a physical defect on metal surface, which is traced by in-situ AFM and it is found that the defect is likely to be preferentially attacked and evolve to pitting corrosion.

Key words: pure aluminum; pitting corrosion; FeCl_3 solution; AFM; uniform attack

1 Introduction

Some in-situ imaging technologies such as video camera[1,2] and CLSM (confocal laser scanning microscopy)[3] have been used in corrosion studies, but the detailed morphological characteristics of surfaces can not be obtained from these methods because they have limited resolutions and are restricted to two-dimensional (2D) imaging. The development of STM (scanning tunnel microscopy) and AFM (atomic force microscopy) in recent years makes it possible to provide high resolution 3D images of a sample immersed in an electrolyte solution under open-circuit condition or under electrochemical controls to enhance our understanding of corrosion mechanism. Because the substrate for STM technique must have a relatively high electrical conductivity, for those self-passivation metals covered with semiconductive protective films, AFM is the more suitable choice for corrosion studies.

Aluminum and aluminum alloys are popular nonferrous metals in industrial application. Protective oxide films are formed spontaneously on their surfaces under air condition, which makes the metal base more resistive to corrosion. However aluminum and its alloys

are susceptible to pitting corrosion in chloride environments owing to the breakdown of the oxide layers. There were some reports on pitting corrosion[4–7] of aluminum alloys induced by intermetallic inclusions in neutral or acidic solution, but few studies were involved with corrosion, especially pitting corrosion of pure aluminum using in-situ AFM technology.

Owing to the oxidation ability of Fe^{3+} , FeCl_3 is often used as an accelerant to examine the resistance of metal to pitting corrosion. In this work, 0.01 mol/L FeCl_3 solution is chosen as corrosive electrolyte, and in-situ AFM is used to investigate the corrosion behavior of 99.9% pure aluminum in FeCl_3 solution. The emphases are focused on pitting corrosion behavior of sample induced respectively by electrochemical polarization and by mechanical destroy of metal surface caused by AFM tip scratching.

2 Experimental

The specimens were cut from pure aluminum foil (99.9%) and were electrochemically polished in a solution containing 75% phosphoric acid, 10% glycerol and 15% distilled water at a current density of 0.2 A/cm² for 4–5 min at 50 °C. The obtained mirror-like surfaces

were etched in 10% NaOH solution for 10 s, rinsed in distilled water and ethanol, dried and stored in air. The corrosive electrolyte was 0.01 mol/L FeCl_3 prepared with distilled water.

The experiments were performed in solution at room temperature with a commercial AFM (SPA400) using Si tips in contact mode. The spring constant of the cantilever is 3 N/m. The imaging progress was performed with a loading force of 1 nN on the tip, and tip scratching process was performed with a loading force of 800 nN. The experiments under open-circuit conditions were performed in an open cell with a volume of 1.5 mL. On the bottom of the cell, the specimen was pasted. The topographical images of the sample surface at different immersion time were traced by AFM. The specimen for electrochemical AFM experiment was placed in special electrochemical cell with a silicone rubber O-ring compressed between the cell and the sample surface. The reference electrode and counter electrode were two Pt wires mounted in the cell with a volume of about 0.7 mL, and insulating tapes were used to seal the aluminum surfaces to exposure a small electrode surface area of

magnification of 150 were obtained through an optical microscope and a CCD camera, then were displayed on the computer screen, to make it convenient to move the AFM tip to the regions of our interest for AFM imaging.

3 Results and discussion

3.1 Corrosion at open-circuit potential

The oxide films formed on aluminum surfaces are slightly soluble in pH value range of 4–9 and are thought to be stable in this pH range. Beyond this range, the oxide films may be chemically dissolved, and the metal base will undergo uniform corrosion[8]. In the case of FeCl_3 , Fe^{3+} is hydrolyzed to form $\text{Fe}(\text{OH})_3$ so that the solution becomes acidic. The pH value of 0.01 mol/L FeCl_3 in this work is measured as 2.30 by a pH sensor, which is within the unstable pH region for aluminum. In-situ AFM images of the non-pitting surface of aluminum in 0.01 mol/L FeCl_3 measured at the beginning (1 min) and 1, 4, 24 h immersion time are shown in Figs.1(a)–(d), respectively.

Fig 1(a) shows the shapes of small convex features



Fig.1 AFM images of non-pitting surface of aluminum surface in 0.01 mol/L FeCl_3 solution at different immersion time: (a) 1 min; (b) 1 h; (c) 4h; (d) 24 h

particles of corrosion product from the pits which are not removed by rinsing process. The element EDAX analysis of these particles is performed and Al, O, Cl, Fe and Cu elements are detected in the particles as shown in Fig.2(c).

The purity of the sample is 99.9%, and there are still 0.1% impurities which may influence the corrosion behavior. Cu and Fe are common impurities in pure aluminum, so Cu in corrosion product comes from impurities. But there are two possible origins for Fe element, that is, impurities and Fe ions in electrolyte. Accompanied with the anodic dissolution of aluminum, both H^+ and Fe^{3+} can be reduced to form H_2 and Fe^{2+} respectively to provide cathodic electrochemical current. But Fe^{2+} ions are voluntary to be oxidized to Fe^{3+} ions by oxygen in the aerated solution. So the particles of corrosion product might be complex compounds comprising hydrates of $Al(OH)_3$, $Fe(OH)_3$, $Al(OH)_xCl_{3-x}$, $Fe(OH)_xCl_{3-x}$, $CuCl_2$ etc.

3.2 Electrochemically induced pitting corrosion

After fixing the aluminum foil sample, introducing 0.01 mol/L $FeCl_3$ solution by micro-injector to the ECAFM cell and finishing connection between the electrodes and potentiostat, potentiodynamic polarization sweep is performed from the open-circuit potential (OCP) to +500 mV relative to OCP at a scan rate of 10 mV/s. From the video images, uprising of hydrogen bubbles from the surface is observed accompanied with pitting corrosion during the polarization. After polarization, a small part of solution is fetched out and reinjected into the cell again to stir the solution slightly to drive the hydrogen bubble away from the surface, then the AFM

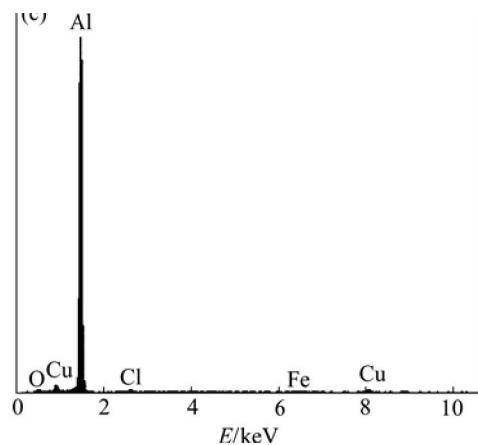


Fig.2 SEM micrographs ((b) is magnified micrograph of marked region in (a) of aluminum surface obtained after 24 h immersion in 0.01 mol/L $FeCl_3$ solution) and EDAX analysis(c) of corrosion product particles

tip is moved to the pitting areas to get detailed topographies. Three pits are chosen to be traced. AFM images of pit 1 and pit 2 are measured as shown in Fig.3(a), and pit 3 in Fig.4(a). To check the effect of imaging scan on the pits, the images of the three pits obtained after a second imaging scan are shown in Fig.3(b) and Fig.4(b). Then another potentiodynamic polarization sweep is performed from OCP to +300 mV relative to OCP at a scan rate of 15 mV/s. After the second polarization course, the detailed AFM images of the three pits are measured again after hydrogen bubble is driven away as shown in Fig.3(c) and Fig.4(c).

The sectional profile along the line in Fig.3(a) is presented in Fig.5, from which we can read the pit depth

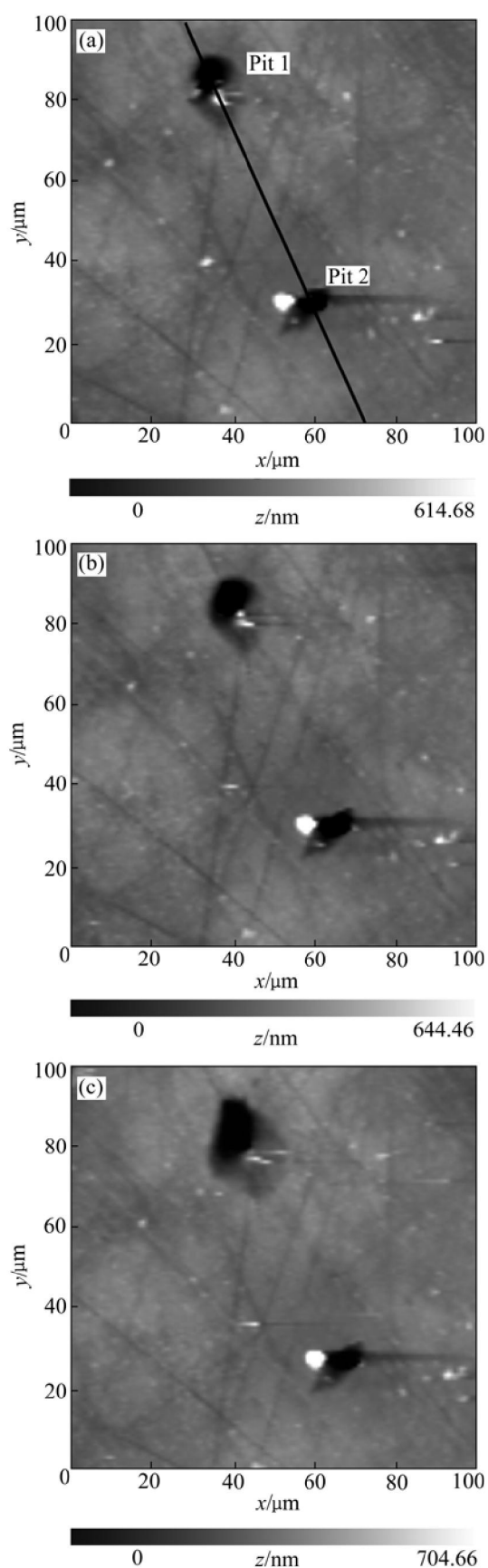


Fig.3 AFM images of pit 1 and pit 2: (a) First imaging scan after first polarization; (b) Second imaging scan after first polarization; (c) Imaging scan after second polarization

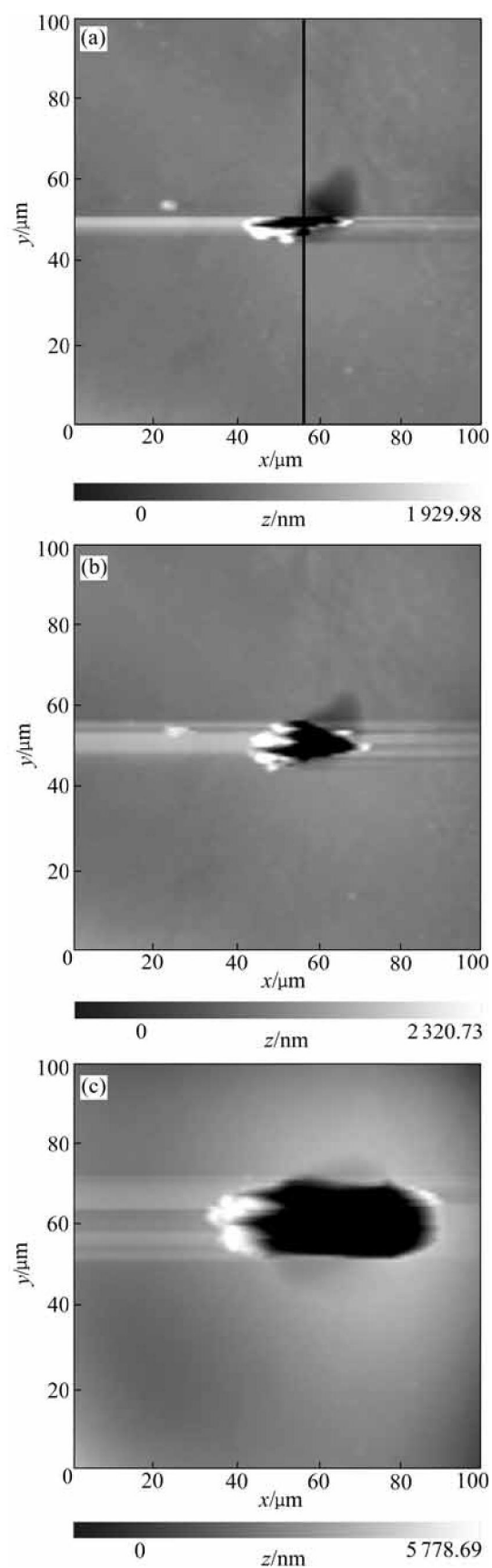


Fig.4 AFM images of pit 3: (a) First imaging scan after first polarization; (b) Second imaging scan after first polarization; (c) Imaging scan after second polarization

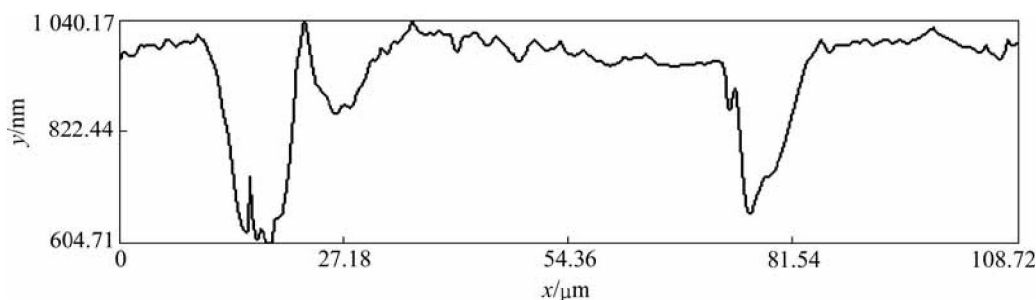


Fig.5 Sectional profile for pit 1 and pit 2 in Fig.3(a)

and orifice diameter. The depths and orifice diameters of pit 1 and pit 2 in Fig.3(a), Fig.3(b) and Fig.3(c) measured along the same line position are recorded, as shown in Table 1. Similarly, the depth and orifice diameter of pit 3 measured at the position along the line as shown in Fig.4(a) are recorded, which are also presented in Table 1.

Table 1 shows that the second AFM imaging scan of pit 1 and pit 2 does not lead to obvious changes (Figs.3(a) and (b)) of pit size. But for pit 3 the second imaging scan enlarges the pit size both in lateral and vertical direction (Figs.4(a) and (b)). This enlargement should be ascribed to the removal of corrosion produce covered on the pit or/and the removal of oxide layers loosely bound to the surface. The removal behavior can not only directly lead to the enlargement of pit size, but also expose the aluminum base to solution to enhance pitting corrosion.

Table 1 Depth and orifice diameter for pits in Fig.3 and Fig.4

Pit	Depth/nm			Width/ μm		
	(a)	(b)	(c)	(a)	(b)	(c)
1	394	401	581	12.220	12.553	16.341
2	294	293	289	12.127	12.120	12.096
3	2 756	3 203	4 457	4.088	14.170	21.101

The quantitative profile analysis in Table 1 demonstrates that from Fig.3(b) to Fig.3(c) the depth and the diameter of pit 1 increase, but a little change of size takes place on pit 2. This is in good agreement with the observation of CCD that during the second polarization, uprising of hydrogen bubbles is observed from the region around pit 1 but not pit 2, meaning that pit 1 which is initiated in the first polarization sweep loses activity and is repassivated in the second polarization sweep. The radius of pit 2 is about 3.5 μm , which is between the radius range of 0.1–6.0 μm for metastable pit described in the research of PRIDE et al[10]. However because from the CCD video it is hard to decide whether the active period for pit 1 is in agreement with the accepted life-span of metastable pit (often within several second [11]), there is still another possibility that pit 2 is not a metastable pit and just dies in the second polarization

scan owing to the change of corrosion environment caused by solution-stirring.

From the changes taken place on pit 1 and pit 3 as shown in Fig.3, Fig.4 and Table 1, we can get the conclusion that pit 3 develops more rapidly in the lateral and vertical direction than pit 1. It is demonstrated that different pitting regions reveal dissimilar activity for pitting corrosion owing to the difference of local physical and electrochemical characterizations. Otherwise the different shapes of pits might be a possible reason for their different developing speed. Pit 3 is a partially-occluded pit covered with corrosion product or oxide layer, and pit 1 is an open one. For the pit 1, the intercommunication among electrolytes within the pit and in the bulk solution is much easier so that the high pH value necessary for autocatalytic pit propagation [12] is relatively difficult to maintain, accordingly its development is tempered compared with pit 3.

3.3 Pitting corrosion induced by AFM tip scratching

It is reported that the AFM tip-surface interaction in corrosive medium can enhance the dissolution rate of metal surface and produce cavities in the scratched areas [13–15]. In this work, AFM tip scratching techniques was used to create an artificial physical defect on the surface of aluminum foil and the topographic changes on the defect region with evolution of immersion time in 0.01 mol/L FeCl_3 were recorded by in-situ AFM.

The surface morphology of a pure aluminum (99.9%) scratched by AFM tip in 0.01 mol/L FeCl_3 solution is shown in Fig.6(a). The square 20 $\mu\text{m} \times 20 \mu\text{m}$ central area is scratched by the tip with a loading of 800 nN for 30 min at a scan frequency of 8 Hz to form an impression. The friction forces between the tip and the sample cause local heating of the substrate, which provides enough energy to overcome the activation barrier for the chemical reaction of chloride anions with metal ions. Meanwhile the tip scratching causes mechanical destroy of the metal surface, as the overall result, the dissolution of the substrate is accelerated[15].

The topographical images measured at the fabricated impression region after 1 h and 6 h immersion in FeCl_3 solution are measured, as shown in Fig.6(b) and

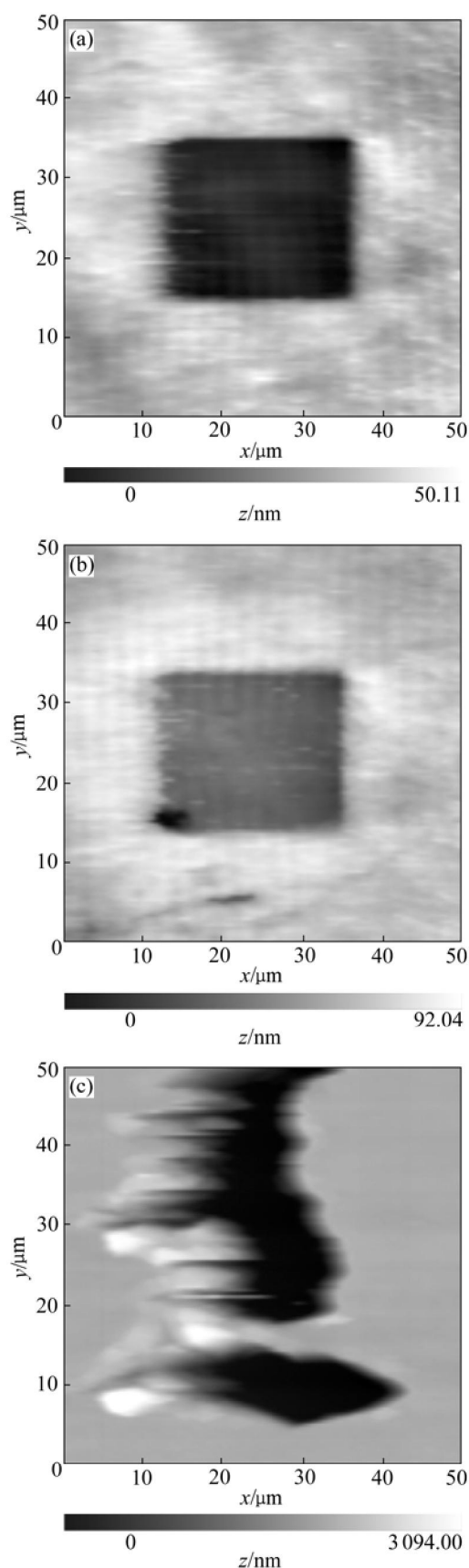


Fig.6 Topographies of artificial impression formed by AFM tip scratching(a) and measured after 1 h(b) and 6 h(c) immersion in 0.01 mol/L FeCl_3

Fig.6(c). After 1 h immersion a new small pit with depth of about 20 nm appears in the bottom left corner of the impression. After 6 h, the scratching formed impression cannot be distinguished and two pits with depth of about 30 μm are observed in this region. The results illustrate that pitting corrosion tends to originate from the scratched area.

Supposing that the contact area between the tip and the surface during the scratching process is equal to the hemispherical area of a radius tip (approximate 20 nm), the intensity of exerted pressure on surface is calculated as 3.17×10^8 Pa. On one hand the strong interaction between the tip and the surface might destroy the protective films (including corrosion product film and oxide film), on the other hand the metal base at scratched position becomes mechanically stressed and physically different from the around region. So the electrochemical activity of scratched region is relatively high and likely to be preferentially attacked in the environment containing chloride ions to develop to pitting corrosion.

In the first 30 min-scratching course to produce the impression in Fig.6(a), the surface of the scratched aluminum has repassivation ability. As a result of the process of surface depassivation caused by the AFM tip scratching, followed by limited dissolution, redeposition of corrosion product and repassivation, the enhanced dissolution is uniform, and a smooth impression with a flat bottom is formed. This is essential erosion corrosion [13]. But after a period of immersion in FeCl_3 solution, the scratched region is preferentially attacked by Cl^- ions and its activity is enhanced. In this case active dissolution overwhelms repassivation, and the high reactivity of bare aluminum ensures rapid localized attack, so self-catalyzed pit corrosion happens and develops with evolution time. Because physical and electrochemical characteristics are most discrepant in the intersection regions between the scratched area and unscratched area, we can find from Fig.6(b) that pit corrosion is originated firstly from the intersection corner, which strongly proves that physical defects have high activity for pitting corrosion.

4 Conclusions

1) The comprehensive researches by AFM, SEM show that 99.9% aluminum sample suffers from general corrosion and pit corrosion in FeCl_3 solution. The redeposition particles of corrosion product are examined by EDAX to be complex compounds possibly comprising hydrates of $\text{Al}(\text{OH})_3$, $\text{Fe}(\text{OH})_3$, $\text{Al}(\text{OH})_x\text{Cl}_{3-x}$, $\text{Fe}(\text{OH})_x\text{Cl}_{3-x}$, CuCl_2 , etc.

2) By in-suit electrochemical AFM studies, the initiation, propagation and repassivation of pitting corrosion of pure aluminum in FeCl_3 solution under

electrochemical controls are successfully observed. Owing to the diversity of physical and electrochemical characterizations, different pitting regions reveal different activities for pitting corrosion under the same polarization conditions.

3) AFM tip scratching technique is used to form an artificial defect on aluminum surface under open-circuit condition in FeCl_3 solution. The in-situ AFM observation of pitting corrosion originated from the artificial impression demonstrates that the physical defects on metal surface have high activity for pitting corrosion, and are likely to be attacked preferentially to pitting corrosion.

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